Distributeur de fournitures pour l'industrie aéronautique en Rhône-Alpes 8 rue du Puits Rochefort Z.I. de Montmartre, 42100 Saint-Étienne, FRANCE +33-(0)4 77 49 36 36

NMB Minebea Spherical, Rod End

and Sleeve Bearings **1997, metric**"

BEARING CLASSIFICATIONS

Bearings are divided into two basic categories:

(1) rolling element or "anti-friction" bearings.

(2) sliding surface or "plain" bearings. Except as noted, all bearings in this guide are of the "plain" bearing classification.

TABLE 1 - NMB BEARING CLASSIFICATION BY CONSTRUCTION ELEMENTS

TABLE 2 - NMB CATALOG BEARING SERIES BY CLASSIFICATION

(Bearing Series listed include both aircraft and commercial types)

NMB manufactures a wide range of spherical bearings and rod ends for both commercial and aerospace applications. Figures 1 through 6 show examples of 2-piece, 3-piece and 4-piece rod ends with configurational variations. All rods end shown are manufactured in both male and female versions. The metal-to-metal rod ends can be furnished with dry film lubricant coatings or, when size permits, be provided with grease lubrication grooves, holes and flush type or zerk type fittings. In general, lube fittings cannot be furnished on rod ends with bores of less than .250" (6.35mm).

RODS ENDS

Figure 1 illustrates a 2-piece swage coined rod end. The head of the rod end is coined or swaged around the ball and thus serves as the outer race. This type of rod end is generally used in static applications when maximum strength in a given envelope is required. By virtue of its design, however, the 2-piece coined rod ends has relatively poor ball to race conformity, particularly in the 6 o'clock area, and Teflon liners are not recommended. On the other hand, the simplicity of its design permits this type of rod end to be manufactured in miniature sizes with bores as small as .0469" (1.191mm).

Figure 2 represents Mohawk configuration. The Mohawk 2 piece design is an economical rod end serving a broad spectrum of commercial application. Figure 2 shows the configuration used for Teflon lined Mohawks. This design has good ball to race conformity and can be used in dynamic applications when loads are relatively light.

FIGURE 3 - 4- PIECE, INSERT-TYPE ROD END

Figure 3 shows a 4-piece insert-type rod end construction. This configuration sees wide usage in commercial and general aviation applications. As catalog items, they are furnished with zinc or cadmium plated steel bodies having an ultimate tensile strength of 82.5ksi (569 N/mm²), ball of through hardened bearing steel, chrome plated, and inserts of either copper alloy or 300 series stainless steel. 4-piece rod ends can be furnished with re-lubrication provisions, but are not available with Teflon liners.

ENGINEERING DATA

BEARING TYPES AND DETAILS OF CONSTRUCTION

Figure 4 and 5 show 3-piece rod ends with 2 types of insert retention. All bearings shown can be furnished in grease lubricated, dry film lubricated or Teflon lined versions. The V-groove staked design illustrated in Figure 4 is the most widely used configuration in aerospace applications. Three V-groove types covering inch bearing sizes 3 through 24 have been standardized by MS bearing and rod end specifications. The V-groove is machined into the race face after swaging. The outer lip formed by this groove is flared over the housing chamfer. This method provides moderate thrust capacity and allows a worn bearing to be removed and replaced with no damage to the housing.

FIGURE 4 - 3- PIECE, V-GROOVE STAKED ROD END

Figure 5 illustrates a housing stake configuration. This method is generally used only when there is insufficient space on the race face for a V-groove, or when other factors such as nonductile race material. Race shear strength or economy of production are considered.

Figure 6 shows a rod end design using the reverse Messerschmidt principle. The ball is not fractured but machined and ground in matched sets with zero gap at the separation plane. The body is usually of hardened CRES, the ball of copper alloy. Worn balls can be removed manually and replaced. Maximum body strength and bearing projected area results from the fact that loader slots are omitted.

FIGURE 5 - 3- PIECE, HOUSING STAKED ROD END

FIGURE 6 - 2- PIECE, SPLIT BALL ROD END

FIGURE 7 - SWAGED SPHERICAL BEARING

design is used when the bearing outer race is not symmetric
about the spherical centerline due to a flange or a wide over
hang on one side or a combination of both. In such case, the
problem side of the race is pre-formed **BALL ASSEMBLY** PRE - FORM RACE

FIGURE 8 - SWAGED PRE - FORM BEARING

FIGURE 9 - LOADER SLOT BEARING

SPHERICAL BEARINGS

Figure 7 illustrate the procedures used in manufacturing a standard type swaged spherical bearing. The finished ball is inserted into the cylindrical race blank by slip fit and installed into the assembly die. After removal from the die, the race O.D. is spherical in shape as shown in the "As Swaged" view. At this stage, the ball and race are locked firmly, together and incapable of relative movement. Following subsequent machining, the bearing assembly is released (loosened) to the torque or radial clearance required and the O.D. is then ground to the finished size.

Figure 8 demonstrates an alternative swaging method used when the bearing geometry precludes or renders impractical the double swaging method shown in figure 7. The pre-form design is used when the bearing outer race is not symmetrical about the spherical centerline due to a flange or a wide overhang on one side or a combination of both. In such case, the problem side of the race is pre-formed by machining and grinding and the opposite side only is swaged.

Figure 9 shows a loader slot, or "Messerschmidt" bearing design. This is a non-swaged bearing type. The spherical I.D. is machined and then precision ground after hardening. The loader slots are profile milled prior to heat treatment. This design permits the ball to be inserted and removed manually in the field without need of tooling. Additional advantages of this design are that extremely close tolerance radial and axial clearances can be attained, and very high strength materials and surface coatings can be used on the outer race. A major disadvantage of the design is the need to properly orient the slots with respect to the applied loads due to the loss of bearing projected area. In addition, it is difficult to retain grease and exclude contaminants unless the loader slots are sealed.

ENGINEERING DATA

Figure 10 illustrates a double fractured race bearing. This type of bearing can be furnished in either a single or double fractured configuration. The retaining ring groove is provided only on the double fractured race design and serves as a recess for a retaining wire or spring which holds the race halves together to facilitate handing until the bearing is installed into its housing. Both race and ball are made of bearing steel, through hardened and precision ground. All surfaces of the ball and race coated with zinc phosphate and a dry film of molybdenum disulfide ($MoS₂$). In addition, lube grooves and lube holes are provided to permit relubrication through either the housing or shaft. For corrosive environments, balls and races of through hardened stainless steel can be furnished. NMB manufactures catalog series of single and double fractured race bearings in both inch and metric sizes. Nitrile rubber (NBR) seals can be provided as option for all sizes.

FIGURE 10 - FRACTURED RACE BEARING

Figure 11 shows two examples of snap-assembled or "pop-in" bearing configurations. When component geometry permits (a relatively large diameter, thin section, narrow ball and race), a bearing may be snap-assembled. Snap-assembly is accomplished by deflecting the race, ball, or both within their elastic limits to allow entry of the ball into the race. This type of design is generally used only when all other methods are impractical or impossible due to problem geometry or processing restraints.

FIGURE 11 - SNAP-ASSEMBLED BEARINGS

ENGINEERING DATA

JOURNAL BEARINGS (SELF-LUBRICATING) MS SERIES

Figure 12 shows the NMB AJ and AHJ series which are approved for procurement to MS21240 and MS81934/1 series respectively.

ROD END BEARINGS - AIRFAME (ANTI-FRICTION) SERIES

''''''''''''''''''''''''''

FIGURE 12 - PLAIN, TEFLON LINED FIGURE 13 - FLANGE, TEFLON LINED

Figure 13 shows the NMB AJF and AHJF series which are approved for procurement to MS21241 and MS81934/2 series respectively.

Figure 14 shows internal construction of a double row ball bearing rod end. Ball bearing rod ends are typically used for low load, low friction, dynamic applications. Configuration permits bearing misalignment to 10° in either direction. Inner rings and balls are made of 52100 steel with bodies made of 4130 steel or 8620 steel. Bearings are cadmium plated for corrosion protection and prepacked in grease. NMB ball bearing rod ends are approved for procurement to AS6039 and MS21150, MS21151, MS21152, and MS21153.

ROLLER BEARINGS (SELF - ALIGNING) MS SERIES

Figure 15 shows various MS series of roller bearing rod ends and bearings NMB roller bearings are approved for procurement to AS8952 & AS8914 and MS21221, MS21223, MS21220, MS21429, MS21431, MS28913 and MS28914.

TEFLON* OR POLYTETRAFLUOROETHYLENE

(PTFE) - has good wear and excellent low friction properties and makes the ideal bases for a self lubricating liner. However, pure PTFE has a very low strength and must therefore be reinforced in some way to produce an acceptable load carrying surface.

NMB Teflon liners have a woven textile backing (such as Glassfiber, Dacron or Nomex) to give required strength , with a PTFE fiber interwoven to provide the self lubricating properties. The PTFE fiber is concentrated towards the front of the liner where the low wear and self lubricating properties are required, with the majority of the reinforcing textile fiber at the back to ensure a good bonding surface. The liner is impregnated with Phenolic resin for added strength. (See Figure 16). A thermosetting bonding agent applied under temperature and pressure ensures a good bond between the liner and the base metal.

SOME CHARACTERISTICS OF THE PTFE LINER

- 1. Modulus of elasticity: 4.5×10^5 psi. $(3.1 \times 10^5$ N/cm²)
- 2. Coefficient of thermal expansion: 11.6×10^{-6} in/in/ \degree F. $(20.9 \times 10^{6} \text{ mm/mm} / {}^{\circ}\text{C})$
- 3. Low coefficient of friction ranging from approximately .02 to .10. As shown in Figure 17, the coefficient decreases as load and temperatures increase. However the coefficient also increases as surface speed and mating surface roughness increase.
- 4. Noiseless in operation.
- 5. Is non-corrosive.
- 6. Resistant to most chemicals, greases and oils, however wear rates may increase when movement takes place under contaminated conditions.
- 7. Is non-conductive and non-magnetic.
- 8. After an initial run-in period, wear rates remain low and relatively constant.
- 9. Can continue to function satisfactorily with wear as high as .010" (0.25mm).

TABLE 3 - CHARACTERISTICS OF FOUR PRINCIPAL NMB LINER SYSTEMS

* A trade name of E.I. duPont de Nemours & Co., Inc.

FIGURE 19 - PTFE BEARING EVALUATION CHART

TORQUE CALCULATION

The prediction of spherical bearing torque is more difficult than that of rolling element bearings. Friction coefficients of the sliding surfaces in these bearings vary depending on temperature and load. Torque at various loads is estimated by using the following formula:

INSTRUCTIONS FOR USE OF EVALUATION CHART

EXAMPLE 1

To select a PTFE-lined bearing to meet your need (for life other than 25,000 cycles):

- (1) Multiply your expected radial dynamic load by the dynamic load factor corresponding to the required life cycles. Example:5,000 lbs. (22,240 N), expected radial load; life requirement 100,000 cycles. Using the chart, 100,000 cycles corresponds to a dynamic load factor of 1.9. Multiplying 5,000 lbs. (22,240 N) By 1.9 = 9,500 lbs. (42,256 N), the equivalent dynamic load.
- (2) Using the equivalent dynamic load of 9,500 lbs. (42,256 N), select any self-lubricated bearing having an oscillating load rating equal to or higher than this amount.

EXAMPLE 2

To determine the expected life cycles for a particular self-lubricated bearing:

- (1) Divide oscillating load rating of bearing by your expected radial load to determine the dynamic load factor. Example 9,500 lbs. (42,256 N) ÷ 5,000 lbs. (22,240 N) = 1.9 dynamic load factor.
- (2) Using 1.9 dynamic load factor, determine the bearing lifeapproximately 100,000 cycle.

PER-LOAD TORQUE

Rotational Breakaway Torque is the highest value attained just prior to ball movement. The ball should be hand rotated through several revolutions immediately before testing.

Rotational Torque is that value required to maintain 2 rpm rotation of the ball about its centerline.

Misalignment Torque is the value required to move the ball in a mode other than rotation.

All torque testing should be performed with the outer race restrained in such a manner as to minimize bearing distortion and the resultant effect on the torque reading obtained. Torque readings can vary appreciably as the result of incorrect clamping, presence of contaminants, excessive speeds and differences in atmospheric conditions. The need, as specified above, for hand rotating the ball through several revolutions prior to checking breakaway torque is extremely important. Because of pre-load between ball and race, the liner, under compression, slowly conforms to the microscopic surface irregularities of the ball. To initiate rotation after a period of time, all of the microscopic liner projections into the ball surface must be sheared off. Once this has been accomplished, the torque reverts back to its rated value. All torque resting should be performed with the outer

Id load. Torque at various loads is estimated by using the

Id load. Torque at various loads is estimated by using the

Id lowing formula:

Id load. Torque at various

GAGING LINED BORES

Conventional bore measuring equipment such as air gages, inside micrometers, etc. will often indicate an apparent oversize condition when used in measuring fabric lined journal bores. Texture and resiliency of the fabric liner as well as the contact pressure exerted by the gaging instruments all contribute to the probability of obtaining a false reading.

The most widely accepted method for inspecting lined journal bores is with the use of plug gages. The diameter of the "go" member should be 0.0008" (0.002 mm) below the minimum bore diameter specified and that of the "no-go" should be .00005" (0.0012mm) larger than the maximum bore diameter specified. The "go" member should enter freely or with light to moderate force. The "no-go" member should not enter with light force but entry under moderate to heavy force is acceptable.

All edges of gage members should have a radius of .030" MIN (0.76mm), and surface finish of the gage should not exceed 8 RMS (0.2 μ mRa) in order to prevent damage to the fabric when inspecting.

FACTORS AFFECTING THE SELECTION, PERFORMANCE AND EVALUATION OF PTFE-LINED SPHERICAL, ROD END JOURNAL BEARINGS

An answer to situations where the performance envelope cannot be covered by metal to metal bearings is to consider PTFE-lined bearings. Here, the lubricant configuration is such that it functions as the load carrying element of the bearing, as represented by the liner systems currently in use. PTFE bearings may be specified under all or some of the following situations:

- 1. Where lubrication is undesirable, difficult to perform, or impossible.
- 2. Where loads are high and angular movement is low. Under these circumstances, rolling element bearings fail rapidly.
- 3. Where space is limited. A PTFE-lined bearing in high loadlow speed environments is usually much smaller in size than a rolling element bearing.
- 4. Where vibration is present. A PTFE-lined bearing is more likely to accept vibration than is a rolling element bearing.
- 5. Where temperature of the environment renders greasing unfeasible.
- 6. Where a joint must remain static for extended long periods of time before movement is initiated.
- 7. Where friction in a greased bearing would be so high as to render the joint area unless after a limited number of cycles or impose an unacceptable fatigue situation.
- 8. Where, in static joints, fretting is a problem.

While PTFE-lined bearings can do an excellent job in many areas, there have been areas of misapplication. Also, there exist some misunderstandings regarding life and failure as applied to hardware of this type. We may define some of these concepts as follows:

- 1. The PTFE-lined bearing starts life with a finite rotational pre-load torque or clearance.
- 2. This rotational pre-load torque always decreases with bearing usage and clearance always increases with usage.
- 3. A bearing may be said to have failed if the rotational preload torque drops below some specified value. This is always a systems application characteristic.
- 4. A bearing may be said to have failed when the clearance generated by wear exceeds some specified value. This, again, is always some specified systems characteristic.
- 5. A bearing may be said to have failed if the liner wears through enough to permit the ball to contact the race.
- 6. No bearing, including PTFE-lined bearings, will last forever. The "Lifetime" lubrication concept applies to the bearing alone, not to the end usage item. Fig. including PTFE-lined bearings, will last forever a joint must remain static for extended long periods
The "Lifetime" lubrication concept applies to the bearing
alone, not to the end usage item.
The presence of liner d
	- 7. The presence of liner debris on a bearing is not a definitive indication of failure.
	- 8. PTFE-lined bearings tend to telegraph their impending failure by increased radial and axial play.

When evaluating the probable service life of a PTFE-lined bearing application, there are some factors that do not appear in the PV = K relationship. Some considerations for a given application might include:

- 1. Surface sliding speed.
- 2. Maximum ambient temperature.
- 3. Size of the heat sink.
- 4. Acceptable friction levels.
- 5. Load per unit of area, or liner stress level.
- 6. Mode of load application; i.e., the duty cycle.
- 7. Service alignment accuracy, particularly with respect to sleeve and flanged bearings.
- 8. Surrounding atmosphere.

Cost is not included in the above list since it does not affect the serviceability of any bearing. Higher individual bearing costs may many times result in a more economical or lower priced finished assembly.

Other aspects of applying PTFE-lined bearings relate to many obscure factors. The airframe industry is a case in particular. They readily accept the L₁₀ life concept in evalu**ating rolling element bearings but tend to reject it in lined bearings. In dealing with the troubleshooting relating to lined bearings at the user level, we may summarize most of them as follows:**

1. Customers specify bearings to certain generalized specifications which may or may not reflect end usage requirements.

- 2. Customers very often have no idea, nor can they define what loads or loading situations the bearings may be subjected to during the design stage.
- 3. Continued upgrading of TBO performance on the part of users may not be consistent with established structural envelopes.
- 4. A marked difference exists between what is acceptable on military aircraft versus civil aircraft. Apparently specification writers overlook this aspect entirely.
- 5. Most customers and users do not realize that life in a lined bearing is limited. They accept this fact on clutches and brakes, but they apparently cannot see the similarity with respect to lined bearings.
- 6. No acceptable criteria have been established with respect to design or acceptable life for this type of bearing. Therefore it is almost impossible for a bearing supplier to initiate all-encompassing test programs.
- 7. Many bearings are removed and replaced because of detectable play between ball and race. Some bearings have been removed that still have specification pre-load torque. We must conclude that the potential service life of the bearing is not being used.
- 8. Confusion exists with regard to liner wear. The term "extruded liner" often noted on field UR's is not sufficiently definitive. Wear debris is normal to this type of bearing and must be differentiated from true liner failure.
- 9. The term "dynamic load rating" or "oscillating load rating" should not be used to select a bearing for an application. These ratings have no relationship to actual applications and relate to a qualification condition only.
- 10. Many line bearings are removed because of fretting between the bearing outer race and the adjacent structure. The use of metal-to-metal bearings will not eliminate this problem. This situation can be cured only by proper selection of materials and interface surface finishes.

GREASE AND DRY LUBRICANTS

FIGURE 21

FIGURE 22

GREASE

When using a fluid (grease/oil) type lubricant, optimum lubrication is achieved when the moving member is supported by a hydrodynamic film. This hydrodynamic film is best generated under operating conditions of light loads and high speed rotation as characterized by typical ball bearing applications. The most common lubricated spherical bearing application, however, is typified by relatively high loads and slow oscillation, seldom by steady rotational movement.

In order to maximize distribution of the lubricant in spherical bearings, a radial clearance between the ball and race should be provided in the free state such that it is maintained after bearing installation. This clearance permits grease to flow between the ball and race surfaces. In addition, lube holes and interconnecting annular lube grooves should be provided as may be required. Annular lube grooves allow for 360° distribution of grease even when the bearing is relubricated under load.

Figure 21 illustrates a lubrication network which provides for lubricating both the ball/race and the ball/shaft (or pin) interfaces. Further, relubrication can be accomplished via the race housing or the ball shaft or pin. If relubrication is to be done via the race housing, and no lubrication is required in the ball bore, lube holes and I.D. lube groove in the ball may be omitted. Conversely, if relubrication is to be done via the shaft or pin, lube holes and O.D. groove in the race may be omitted.

Figure 22 shows a transverse lube groove configuration for use on medium to large size spherical bearings in critical applications where lubrication demands are more extreme. The transverse grooves are machined into the cylindrical race blank prior to swaging. These bearings are often bushed with copper alloy sleeves which in turn may incorporate transverse or equivalent lube groove patterns to provide for maximum possible lubrication.

TABLE 4 - GREASE LUBRICANTS

GREASE AND DRY LUBRICANTS

TABLE 5 - DRY FILM LUBRICANTS

Table 4 shows three most common grease lubricants used in NMB bearings and rod ends. Rod ends requiring relubrication are generally furnished with zerk type or flush type lube fittings except in those cases where relubrication is to be accomplished via the shaft or pin.

Proper, periodic relubrication of grease lubricated spherical bearings is essential to optimum bearing performance and long service life. Frequent relubrication reduces wear and friction, prevents fretting and galling, and minimize chemical corrosion. Experiment the shaft or pin.

Table 5 lists two common types of dry film lubricants

wary from 200° to 1,000°F (93° to 538°C). Both organized

Table 5 lists two common types of dry film lubricants

wents fretting and galli

DRY FILM

Dry film, also referred to as "solid film", lubricants are generally used in applications which preclude the use of grease lubricated or PTFE lined bearings. In certain cases, however, they may be used as a "back-up" for grease lubricated bearings.

The majority of dry film lubricants consist of $MoS₂$ and small quantities of other materials, such as graphite or powered metals. Coatings may be applied by spraying, brushing or dipping and are hardened by cure baking at temperatures which may vary from 200° to 1,000°F (93° to 538°C). Both organic resins and inorganic binders may be used.

Table 5 lists two common types of dry film lubricants used in aerospace bearings. In addition to these, however, NMB uses a wide variety of dry film compounds selected by our engineers to best meet the requirements of specific applications. Dry film selection factors include:

- Temperature Range
- Compatibility with oils and greases
- Static load capacity
- Dynamic wear characteristics
- Exposure to extreme environments, i.e., vacuum LOX, radiation, etc.

LOCKING DEVICES, KEYS AND KEYWAYS

Keys are represented here are metallic locking devices which, when assembled into keyways and keyslots, prevent relative motion between mating components of bearing linkage assemblies.

NMB does not supply keys, nuts or lock wire as separate items. These items are readily available from other sources.

Keyways and keyslot are optional. To specify, add suffix "W" to NMB catalog rod end part number.

NAS 1193 KEY

NAS 1193 KEY, TYPICAL INSTALLATION

NOTES:

- 1. NAS 1193 keys are for positive indexing. They are used in applications in which a fine adjustment is required, within .001 inches.
- 2. These keys can be used in conjunction with NAS 513, NAS 559 and AS81935/3 keyways or keyslots are available for thread sizes 1/4 through 2-1/4 inches.

LOCKING DEVICES, KEYS AND KEYWAYS

NAS 559 TYPE A KEY

NOTES:

- ➀The keyways and keyslots used in conjunction with these keys are shown in Fig. 25 and Fig. 26. The NAS 559 keys are available for thread sizes 1/4 through 2-1/4 inches.
- ➁Keyway flat may vary from standard on smaller size rod ends but shall extend at least beyond minimum thread length in all cases.

ENGINEERING DATA

AS81935/3 key NOTES:

- 1. AS81935/3 keys are used on AS81935 sizes -3 through - 8 when optioned. The keyways and keyslots used in conjunction with these keys are shown in Fig. 27 and Fig. 28.
- ➁AS81935/3 keys are available for thread sizes 1/4 through 1/2 inches.

BEARING INSTALLATION AND RETENTION

GENERAL

A bearing in the free state is not a functioning bearing. Its performance begins only after its has been installed into its end assembly, and the methods, fits and forces applied in installation will often determine its success or failure in service.

A surprising percentage of early bearing failures can be traced directly to improper mounting conditions. Some examples of frequently occurring installation errors are:

(1) excessive interference fit between housing bore and bearing O.D. (2) improperly designed staking tools. (3) excessive staking forces applied.

The following pages are offered not as a comprehensive guide to answer all questions regarding fits, installation, retention, etc., but rather to point out to the bearing user certain areas that require attention and consideration if the installation is to provide for optimum bearing performance and life.

HOUSINGS

The housing into which the bearing is to be mounted should be designed to ensure the structural integrity and dynamic performance capability of the bearing. NMB offers the following housing design recommendations:

- 1. Bearing-to-housing fit: (See table 7).
- 2. Bore finish : 32 RMS (0.8 µmRa)
- 3. Roundness within the bore diametrical tolerance.
- 4. Bore perpendicular to housing faces within .002" (0.05 mm).
- 5. Housing width : uniform within .005" (0.13 mm) to ensure staking integrity.
- 6. Maximum edge breaks of .005" (0.13 mm) when housing is to be staked over bearing.
- 7. Chamber sizes as calculated per figure 29 formula for Vgroove staking retention.
- 8. Provide for plating or other surface treatments (as may be required) if housing and bearing are of dissimilar metals. (See table 6).

Another material consideration, in addition to dissimilar metals, is that of differing coefficients of thermal expansion between the bearing and housing materials. When the bearing is to be operating over a broad temperature range, and the mating bearing and housing have different coefficients of expansion, special adjustments may be required in the bearing to housing fit to prevent either excessive looseness or excessive torque at temperature extremes. Finish 1.32 RMS (0.8 umRa)

als, is that of different coefficients of thermal expansion b

tween the bearing and housing materials. When the bearing

to be operating over a broad temperature range, and the materials of th

TABLE 6 - TREATMENTS TO PREVENT GALVANIC CORROSION OF DISSIMILAR METALS

 $X = Incompatible$

A = Anodize aluminum per MIL-A-8625,Type II, or Alodine per MIL-C-5541

C = Cadmium plate per AMS-QQ-P-416, Type I, Class2

S = Satisfactory for use with no surface treatment required.

TABLE 7 - HOUSING BORE TOLERANCES FOR METAL TO METAL AND PTFE LINED BEARINGS NBLE 7 HOUSING BORE TOLERANCES FOR METAL TO METAL AND PTFE LINED BEARINGS
BEARING BORE TOLERANCES FOR METAL TO METAL AND PTFE LINED BEARINGS
Tolerances Fit-up

BEARING INSTALLATION AND RETENTION

ENGINEERING DATA

SPHERICAL BEARING INSTALLATION

Use of an arbor press or hydraulic press is recommended. Under no circumstances should a hammer or any other type of shock including impact method be used. A suitable installation tool (as shown in Figure 30) is advised. A guide pin aligns the ball in a 90° position, but all force is applied to the outer race only. A lead chamfer or radius on either the bearing or housing is essential.

STAKING PROCEDURE:

- 1. Install bearing into housing per Figure 30 and position it symmetrical about housing centerline within .005" (0.127 mm).
- 2. Mount bearing and top anvil over bottom anvil guide pin as shown in Figure 31.
- 3. A trial assembly should be made for each new bearing lot to determine the staking force necessary to meet the axial retention load required. Excessive force should be avoided since this may result in bearing distortion and seriously impair bearing function and life. (See Staking Force, Page 21.) al assembly should be made for each new bearing lot
be a cause for eigening the staking force necessary to meet the axial
http://dological.com/should not be a cause for rejection providing bearing meet
bearing function and

LINED JOURNAL BEARING INSTALLATION

The same general procedure as outlined for spherical bearings should be followed. (See Figure 30). In the case of fabric Lined bores, however, it is mandatory that both the insertion tool guide pin and the mating shaft have ends free of both burrs and sharp edges. A .030" (0.76 mm) blended radius or 15° lead (as shown in Figure 34) is recommended, since it is virtually impossible to install a sharp edged shaft without inflicting some damage to the fabric liner. For maximum support of the fabric lined bore, the effective length of the insertion tool guide pin should exceed the journal bearing length.

V-GROOVE RETENTION (V-GROOVE SERIES)

For bearings with race staking grooves, a double anvil staking method as shown in Figure 31 is recommended. This method is best performed on a hydraulic or pneumatic press.

- 4. Apply the staking force established by trial assembly, rotate assembly 90° and re-apply force. Repeat operation through a minimum of 3 rotations to ensure 360° uniformity of lip swaging.
- 5. After staking, a slight gap may exist between race lip and housing chamfer as shown in detail in Figure 31. This gap should not be a cause for rejection providing bearing meets the thrust load specified.

HOUSING STAKE RETENTION (CHAMFERED BEARING SERIES)

Retention of chamfered bearings may be accomplished by many methods and may vary according to housing configuration, material, hardness and the axial thrust load requiered When axial loads are light to moderate, a housing ring staking tool as shown in Figure 32 may be used. The bearing and housing are supported by an anvil while the annular staking tool is forced into one side of the housing flaring a small amount of the housing material over the race chamfer. The opposite side of the housing is then staked in the same manner. When this method is used, the housing crosshole edges should be sharp to a .005" (0.13 mm) maximum radius or chamfer. As with the V-groove staking, excessive staking forces should be avoided in order to prevent deformation of the spherical bearing.

ENGINEERING DATA

BEARING INSTALLATION AND RETENTION

TABLE 8 - V-GROOVE STAKING FORCE

STAKING FORCE

The force required to stake V-groove bearing is approximately equal to the product of the O.D. and a constant for each groove size. For example, a 1.500" (38.10 mm) O.D. bearing having a "B" size groove should require a staking force of approximately 18,000 lbs (80064 N). Constants shown in Table 8 are based on outer race material having an ultimate tensile strength of 140,000 psi (984.6 N/mm²). Staking force constants for other materials are proportional to the ultimate tensile of those materials as compared to 140,000 psi (984.6 N/mm²). Staking forces derived by this formula should be used as a reference guide only to establish a starting point. Please refer to STAK-ING PROCEDURE steps outlined on page 22. Figure 36 shows the test set-up specified in AS81935

lual to the product of the O.D. and a constant for each groove

This is the generally accepted method used by s

This is the generally accepted method used by s

This i

FIGURE 36 - STAKING BEARING PROOF LOAD TEST METHOD

PROOF LOADING

Figure 36 shows the test set-up specified in AS81935 for axial static proof load testing of rod ends with V-groove staked inserts. This is the generally accepted method used by spherical bearing and airframe manufactures for checking axial retention of the stake. The rod end assembly is mounted on a rigid ring which clears the flared O.D. of the insert and supports the rod end body only. The axial proof load is applied to the ball face, the bearing is then reversed 180° and the axial load is repeated on the opposite side.

The approximate proof load can be estimated from TABLE 9.

TABLE 9 - THRUST LOADS BASED ON FIGURE 35 GROOVE TYPES AND MATERIALS SPECIFIED

FIGURE 38

DEFINITIONS FOR ROD END AND SPHERICAL BEARING TERMINOLOGY

Radial Load

A load applied normally to the bearing bore axis. (See Figure 37).

Axial Load

A load applied along the bearing bore axis. (See Figure 37).

Static Load

Is the load to be supported while the bearing is stationary.

Dynamic Load

Is the load to be supported while the bearing is moving.

Static Radial Limit Load *

That static load required to produce a specified permanent set in the bearing. It will vary for a given size as a function of configuration. It may also be pin limited or, may be limited as a function of body restraints as in the case of a rod end bearing. Structurally, it is the maximum load which the bearing can see once in its application without impairing its performance.

Static Radial Ultimate Load *

That load which can be applied to a bearing without fracturing the ball, race or rod end eye. The ultimate load rating is usually, but not always, 1.5 times (1.25 times for rod end) the limit load.

Static Axial Limit Load

That load which can be applied to a bearing to produce a specified permanent set in the bearing structure. Structurally, it is the maximum load which the bearing can see once in its application without impairing its performance.

Static Axial Ultimate Load

That load which can be applied to a bearing without separating the ball from the race. The ultimate load rating is usually, but not always, 1.5 times the limit load.

Axial Static Proof Load

That axial load which can be applied to a mounted spherical bearing without pushout of the bearing from the rodend body.

Fatigue Load

That load which can be applied a rod end bearing withstanding a minimum of 50,000 cycles of alternate load. The loading shall be tension-tension with 100% of fatigue load and 10% of fatigue load.

*** LOAD CAPACITY FOR NECK BALL TYPE BEARINGS**

Load figures given on the Table of Dimension are based on outer race load capacity.

Pin deformation due to fit, hardness and so on may result in crack of ball (inner race).

OSCILLATING RADIAL LOAD OR DYNAMIC LOAD

The uni-directional load producing a specified maximum amount of wear when the bearing is oscillated at a specified frequency and amplitude. This rating is usually applied to self-lubricating bearings only. The dynamic capability of metal to metal bearings depends upon the degree and frequency of grease lubrication, and that of dry film lubricated bearings upon the characteristics of the specific dry film lubricant applied.

RADIAL PLAY

Radial play (or radial clearance) is the total movement between the ball and the race in both radial directions less shaft clearance (when applicable). US military specifications have established the gaging load at 5.5lbs. (24.5 N) and this is now considered as the industry standard (See Figure 42). Unless otherwise specified, the industry wide standard for metal-tometal spherical bearing and rod end radial clearance is "freerunning to .002" (51 µm) MAX" Radial play is sometimes referred to as "Diametral play". The two terms are synonymous.

AXIAL PLAY

Axial play (or axial clearance) is the total movement between the ball and the race in both axial directions. The gaging load at again 5.5lbs. (24.5 N). Axial play is a resultant, being a function of radial play, of ball diameter and race width. The ratio between radial and axial play varies with bearing geometry.

TORQUE

(See Self-Lubricating Liner Systems Section).

TORQUE METER

FIGURE 41 - AXIAL TEST FIXTURE

FIGURE 42 - METHOD OF MEASURING RADIAL PLAY

ENGINEERING DATA

LOAD RATINGS

The load rating of a bearing is determined by the dimensions and strength of its weakest component. External factors, such as mounting components, pins, bolts, and housings are not considered part of a bearing when load ratings are investigated but should be considered separately.

SPHERICAL BEARING LOAD RATINGS

The weakest part, or load-limiting area, of a spherical bearings is its race. For this reason, formulas have been developed that use the race to calculate static load ratings based on size and material strength. The static load rating formulas for self-lubricating and metal-to-metal spherical bearings are shown in figure 43 and 44. These formulas will yield approximate ratings, which should be used as ballpark numbers for bearing design.

The allowable radial stress figures given in the tables were determined from the ultimate tensile strength specifications for various race materials. Allowable axial stress figures were derived from material yield strengths.

Allowable Stress Teflon X-1820 Lined Bearings (psi)

FIGURE 44 - Static load rating formulas for metal to metal spherical bearings.

Allowable Stress Metal To Metal Bearings (psi)

Rod end bearing load ratings can be generated only after carefully determining the load restrictions that each element of the rod end bearing imposes on the entire unit. It order to generate a frame of reference, consider the rod end bearing as a clock face, with the shank pointing down to the 6 o'clock position. The limiting factors in rating a rod end bearing are as follows:

- 1. The double shear capability of the bolt passing through the ball bore.
- 2. The bearing capability, a function of race material or selflubricating liner system.
- 3. The rod end eye or hoop tension stress in the 3 o'clock-9 o'clock position.
- 4. The shank stress area, as function of male or female rod end configuration.
- 5. The stress in the transition area between the threaded shank transition diameter and the rod end eye or hoop.

Most rod ends will fail under tension loading in about the 4 o'clock-8 o'clock portion of the eye or hoop. The hoop stress area (HSA) can be found as follows:

$$
\mathsf{HSA} = .008762 \times D^2 \times \mathsf{Sin}^1 \frac{T}{D} + \frac{T}{2} \times \sqrt{D^2 \cdot T^2} \cdot B \times T
$$

The shank stress area (SSA) is a function of being either male or female, as follows: For the male:

 $SSA = (minor thread diameter)^{2}/4$

For the female:

 $SSA = [J²-(major thread diameter)²]/4$

Pin shear stress (PSS) for a load "F" is as follows: $PSS = \frac{2F}{d^2}$

The axial load capability of a rod end is a function of the following:

- 1. The retention method used to mount the bearing in the rod end eye.
- 2. The axial load capability of the bearing element.
- 3. The bending moment, if any, placed on the rod end.
- 4. The race half width $\frac{1}{2}$ of the bearing element.

This is a function of the axial projected area (APA) of the bearing.

 $APA = (\frac{1}{2})^2$

ENGINEERING DATA

FORMULA FOR DETERMINING MISALIGNMENT OF ROD END & SPHERICAL BEARINGS

STANDARD METHOD MOST STANDARD ROD END & SPHERICAL BEARING MIS-ALIGNMENT ANGLES SPECI-FIED IN NMB CATALOGS ARE BASED ON THIS METHOD.

DESIGN REFERENCE THIS METHOD MAY BE USED AS DESIGN REFERENCE FOR INSTALLATION PURPOSES, BUT SHOULD NOT BE USED AS A FUNCTIONING MISALIGN-MENT UNDER LOAD.

The misalignment angle of a rod end or spherical bearing refers to the angle between the ball centerline and the outer member centerline when the ball is misaligned to the extreme position allowed by the clevis or shaft design, as applicable.

NOTE:

SINCE ANGLE "a" APPLIES EQUALLY ON BOTH SIDES THE CENTERLINE, IT FOLLOWS THAT TOTAL MISALIGN-MENT OF THE BEARING IS DOUBLE THE VALUE OBTAINED FOR "a".

Figure 46 through 49 illustrate varying types of bearing misalignment and a formula for calculating each.

WHERE;

HOW NMB SPECIFIES CATALOG BEARING AND ROD END MISALIGNMENT

Figure 51 illustrates how misalignment angles for standard ball spherical bearings and rod ends are represented in NMB catalog. The misalignment angle is calculated per Figure 46 formula. Neck ball (high misalignment) bearings and rod ends are represented in the same manner, but are calculated per Figure 48 formula.

NMB prefers not to use rod end clevis misalignment for the following reason. The rod end clevis misalignment formula presupposes a clevis configuration as shown in Figure 49 in which the clevis slot and ball faces are of equal width and in direct contact. In aircraft applications the configuration shown in Figure 51 is more typical than that of Figure 51 is more typical than that of Figure 49. As pictured in Figure 51, the clevis slot is wider than the ball to permit installation of flanged bushings and/or spacers. This results in a higher but more variable misalignment capability and the angle of misalignment becomes a function of the user's bushing flange or spacer diameter instead of the fixed rod end head diameter.

PV Factor

While not a type of loading, the PV factor is very useful in comparing and predicting test results on high speed-low load applications such as helicopter conditions.

PV is the product of the stress (psi or N/mm²) and the velocity (fpm or m/min) applied to a bearing. Caution must be advised when considering extreme values of psi (N/mm²) and fpm (m/ min). The extreme must be considered individually as well as together.

Because the PV factor is derived from the geometry and operating conditions of a bearing, it serves as a common denominator in comparing or predicting test results.

The formula for determining the PV value for a spherical bearing is as follows:

 $PV = (x)$ (cpm) (D_B) (psi) (.00073) Where:

 $x =$ Total angular travel in degrees per cycle

cpm = cycles per minute

 $DB = ball$ diameter

psi = bearing stress (use N/mm2 for metric)

Dynamic Oscillating Radial Load

The dynamic oscillating radial load ratings given in this catalog for HT, WHT, HTL and WHTL series self-lubricating spherical bearings are based on testing in accordance with AS81820. For conditions other than those specified by AS81820 for catalog part number, use the formula given below to predict wear.

$$
W = \frac{C}{(\frac{Ln^{2.13}}{La}) \times \frac{(100)}{X} \times 25,000} \times .0045
$$
 (114mm)

Where:

 $W =$ calculated wear

 $C = actual total cycles$

 L_R = rated dynamic load (see product tables)

 L_A = actual dynamic load

 $x =$ total angular travel in degrees per cycle

For special self-lubricating bearings that do not appear in this catalog, determine the radial projected area and multiply by 39,900 psi (275 N/mm²). This determines L_{B} , and the formula can then be used to predict wear.

LOAD DEFINITIONS (Rod End Bearings, Anti-Friction Bearings) Pod End Bearings, Anti-Friction Bearings)

RADIAL LOAD - A load applied normal to the bearing bore axis.

AXIAL LOAD - A load applied along the bearing bore axis.

RADIAL LIMIT LOAD - The static load required to produce a specified increase in radial play or permanent set in the bearing structure.

Values are based on the basic relationship: Limit Load (lbs)= KND2 ,

where:

- $K =$ Load Rating Constant (typically 3200 for rod end bearings)
- N = Number of Balls
- D = Ball Diameter (inch)

AXIAL LIMIT LOAD - The static load required to produce a specified increase in axial play or permanent set in the bearing structure.

FRACTURE LOAD, RADIAL OR AXIAL - The load that can be applied to a bearing without fracturing parts or preventing free turning by hand.

The fracture load rating is usually 1.5 times the limit load.

DYNAMIC RADIAL LOAD - Load based on average "L-50" life of 10,000 complete 90° oscillatory cycles. Bearing failure is based upon inspection for evidence of pitting or surface fatigue on the balls or raceways.

Load ratings for a greater number of cycles may be determined by multiplying the basic load rating by a factor obtained from the life factor chart. (Figure 52)

SPHERICAL BEARING [SELF-LUBRICATING] **SBT**

Dimensions in mm

Notes

1. Teflon liner permanently bonded to race I.D.

- 2. Made to order only.
- 3. No Load Rotational Breakaway Torque. Low Torque All Size: 0.02N · m MAX (Radial Clearance 0.05mm MAX)
- ◯ Please consult MINEBEA for availability of bearings in this series.

MBT V

Dimensions in mm

Notes

1. Teflon liner permanently bonded to race I.D.

- 2. MBT & MBT-V weights are similar.
- 3. Made to order only.
- 4. No Load Rotational Breakaway Torque.

Low Torque All Size: 0.02N · m MAX

(Radial Clearance 0.05mm MAX) ◯ Please consult MINEBEA for availability of bearings in this series.

MBWT-V

Notes

- 1. Teflon liner permanently bonded to race I.D.
- 2. MBWT & MBWT-V weights are similar.

3. Made to order only.

- 4. No Load Rotational Breakaway Torque. Low Torque All Size: 0.02N · m MAX (Radial Clearance 0.05mm MAX)
- ◯ Please consult MINEBEA for availability of bearings in this series.

Dimensions in mm

MBYT-V

Dimensions in mm

Notes

1. Teflon liner permanently bonded to race I.D.

2. MBYT & MBYT-V weights are similar.

3. Made to order only.

4. No Load Rotational Breakaway Torque. Low Torque All Size: 0.02N · m MAX (Radial Clearance 0.05mm MAX)

MBG-VCR

Notes

1. MBG - CR & MBG - VCR weights are similar.

2. Made to order only.

3. Radial Clearance All Size: 0.051mm MAX

MBW-VCR

Dimensions in mm

MINEBEA Part No. ϕ B H7 φD Ω 0.013 W $\overline{0}$ -0.13 H -0.13 α (deg.) φO Ref. SφDB Ref. Staking Groove Static Limit Load kN Approx Weight g S 0 0.25 X 0 0.25 R 0 - 0.25 P 0 - 0.4 Radial **Axia** MBW5CR/MBW5VCR 5 16.0 11.0 8.5 15 7.8 13.494 0.5 1.0 0.4 0.7 59.03 10.68 13 MBW6CR/MBW6VCR 6 16.0 11.0 8.5 15 7.8 13.494 0.5 1.0 0.4 0.7 59.03 10.68 13 MBW8CR/MBW8VCR 8 17.5 8.0 14 10.9 15.478 63.74 8.51 14 MBW10CR/MBW10VCR 10 21.0 12.5 10.5 8 12.2 17.462 0.7 1.4 0.5 1.0 94.43 16.37 23 MBW12CR/MBW12VCR 12 26.0 16.0 13.0 10 15.4 22.225 148.08 39.61 46 MBW14CR/MBW14VCR ¹⁴ 28.0 17.0 14.0 ⁸ 18.9 25.400 182.40 45.99 ⁵⁵ MBW14CR/MBW14VCR 14 26.0 17.0 14.0 6 16.9 25.400
MBW15CR/MBW15VCR 15 29.0 18.0 11 19.0 26.194 188.28 188.28 59 MBW16CR/MBW16VCR 16 30.0 19.0 15.0 10 19.2 26.988
MBW18CR/MBW18VCR 18 33.0 20.0 ... 10 20.4 28.575 2.0 1.5 207.90 52.75 65 MBW18CR/MBW18VCR 18 33.0 20.0 16.0 ² 20.4 28.575 0.7 0.5 235.35 60.11 80 $MBW20CR/MBW20VCR$ 20 35.0 22.0 13 22.9 31.750 260.85 260.85 91.1 260.85 261.1 260.85 MBW22CR/MBW22VCR 22 41.0 22.0 19.0 6 27.1 34.925 2.0 2.0 1.5 341.27 84.72 150 MBW25CR/MBW25VCR 25 54.0 35.0 25.0 15 32.3 47.625 612.91 612.91 146.11 400
MBW28CR/MBW28VCR 28 60.0 35.0 25.0 16.00 36.8 50.800 854.10 654.10 146.11 490 MBW28CR/MBW28VCR 28 60.0 33.0 23.0 14 36.8 50.800 654.10 654.10 140.11 490
MBW30CR/MBW30VCR 30 64.0 37.0 26.0 14 40.4 54.769 16 733.53 157.88 590 MBW30CR/MBW30VCR ADIFOR AERO

Notes

1. MBW - CR & MBW - VCR weights are similar.

2. Made to order only.

(3) For below 4mm in Bore size, bearings are without lubrication grooves.

4. Radial Clearance All Size: 0.051mm MAX

Notes

1. MBY - CR & MBY - VCR weights are similar.

2. Made to order only.

(3) For below 4mm in Bore size, bearings are without lubrication grooves.

4. Radial Clearance All Size: 0.051mm MAX

◯ Please consult MINEBEA for availability of bearings in this series.

Dimensions in mm

SPHERICAL BEARING [MOLD TYPE]

BM SPHERICAL | MOLD TYPE | MINELON®

Materials

Dimensions in mm

Notes

- ① Operating temperature range: -50 °C \sim + 100 °C
- ② Dynamic Load Ratings: Cd
- 1. Reversing & Alternating Load Dynamic Load Ratings shall be reduced by half from the values given in the table under the use of reversing and alternating load condition.
- 2. Factor of Operating Temperature and Sliding Speed Dynamic Load Ratings shall be determined by formula below under the use of High-Temperature and Sliding-Speed condition. Cdt・v=ft・fv・Cd Cdt・v: Dynamic Load Ratings under the use of High-Temperature and Sliding speed.
	- ft: Coefficient of Temperature
	- fv: Coefficient of Sliding speed

Table 1

Table 2

③ Static Load Ratings: Cs

1. Dynamic Load Ratings shall be reduced to one-thirds of the values given in the table under the use of that High-Load will be applied continiously or periodically and be reduced to one-sixth of the values given under Reversing and Alternating Load and Impact Load conditions. 2. Pactor of Operating Temperature and Siding Speed

2. Pactor of Operating Load Ratings shall be reduced by half from the values given

2. Pactor of Operating Temperature and Siding Speed

2. Pactor of Operating Temperatu

Factor of Operating Temperature

Dynamic Load Ratings shall be determined by formula below under the use of High-Temperature conditions. Cs・t=ft・Cs

Cs・t: Dynamic Load Ratings under the use of High-

- Temperature condition.
	- ft: Coefficient of Temperature
	- Cs: Static Load given in the table

Table 3

④ Thrust Load: Pt

Please use thrust load in the range, which does not exceed the thrust load (Table 1 application under temperature environment) from catalogue, and "1/3 of Actual radial Load."

○ Please consult MINEBEA for availability of bearings in this series.

Tolerances

Bm & Dm indicate averages of I.D. & O.D..

2 PIECE ROD END BEARING [SELF-LUBRICATING]

No Letter Indicates Right Hand Thread Letter "L" Indicates Left Hand Thread For X-1276 LINER add suffix "D"

Basic Part No.

- 1. Teflon liner permanently bonded to Body I.D.
- 2. Oscillation load shall be kept within the static load range, as Teflon liner load endurance is greater than body breaking load.
- 3. Made to order only. (from RBT15E to RBT30E)
- 4. No Load Rotational Breakaway Torque. Standard All Size: $0.02 \sim 0.34$ N · m Low Torque All Size: 0.02N · m MAX (Radial Clearance 0.05mm MAX)
- ◯ Please consult MINEBEA for availability of bearings in this series.

2 PIECE ROD END BEARING [SELF-LUBRICATING]

 $\mathbf{R} \mathbf{B}^{\prime}$

ROD END FEMALE 3. SELF-LUBRICATING 2 PIECE **Materials** BODY 303 Stainless Steel BALL 440C Stainless Steel LINER Teflon / Fabric **Description of Types** RBT D L XX I No Letter Indicates Standard Breakaway Torque Letter "T" Indicates Low Breakaway Torque **Bearing Bore Code** No Letter Indicates Right Hand Thread Letter "L" Indicates Right Hand Thread

Dimensions in mm

Notes

1. Teflon liner permanently bonded to race I.D.

2. Oscillation load shall be kept within the static load range,

as Teflon liner load endurance is greater than body breaking load.

3. Made to order only. (from RBT15 to RBT30)

4. No Load Rotational Breakaway Torque. Standard All Size: $0.02 \sim 0.34N \cdot m$ Low Torque All Size: 0.02N · m MAX (Radial Clearance 0.05mm MAX)

3 PIECE ROD END BEARINGS 〔SELF-LUBRICATING〕 **HRT-E**

MALE ROD ENDS SELF-**LUBRICATING** 3 PIECE **Materials** HRT-E HRT-ECR BODY Chromium-Molybdenum Steel SUS630 Stainless Steel Zinc Plated Passivated RACE 410 Stainless Steel / Heat Treated 410 Stainless Steel / Heat Treated BALL 440C Stainless Steel / Heat Treated 440C Stainless Steel / Heat Treated LINER Teflon / Fabric Teflon / Fabric **Description of Types** HRT D L xx E CR T No Letter Indicates Standard Breakaway Torque Letter "T" Indicates Low Breakaway Torque No Letter Indicates Chromium-Molybdenum Steel Letter "CR" Indicates SUS630 for Body Basic Part No. **Bearing Bore Code** No Letter Indicates Right Hand Thread Letter "L" Indicates Left Hand Thread

For X-1276 LINER add suffix "D"

Basic Part No.

- 1. Teflon liner permanently bonded to race I.D.
- (2) Axial load indicates either the smaller value of static load or proof load.
- (3) Special specification can bare higher fatigue load.
- 4. Made to order only.
- 5. No Load Rotational Breakaway Torque. Low Torque All Size: 0.02N · m MAX (Radial Clearance 0.05mm MAX)
- ◯ Please consult MINEBEA for availability of bearings in this series.

3 PIECE ROD END BEARINGS 〔SELF-LUBRICATING〕 HRT

Basic Part No.

eMINEBEA.COM

Minet

Dimensions in mm

- 1. Teflon liner permanently bonded to race I.D.
- (2) Axial load indicates either the smaller value of static load or proof load.
- (3) Select Type "CR" for higher load capability.
- 4. Made to order only.
- 5. No Load Rotational Breakaway Torque. Low Torque All Size: 0.02N · m MAX (Radial Clearance 0.05mm MAX)
- ◯ Please consult MINEBEA for availability of bearings in this series.

3 PIECE ROD END BEARINGS 〔METAL TO METAL〕 **HR-E**

MALE ROD ENDS METAL TO METAL 3 PIECE

Materials

HR L xx E CR F

Basic Part No.

- (1) Axial load indicates either the smaller value of static load or proof load.
- (2) Special specification can bare higher fatigue load.
- 3. Made to order only.
- 4. Radial clearance All Size: 0.051mm MAX
- ◯ Please consult MINEBEA for availability of bearings in this series.

3 PIECE ROD END BEARING 〔METAL TO METAL〕

HR

suffx "FAS" to part No. e.g. HR5FAS

No Letter Indicates Right Hand Thread Letter "L" Indicates Left Hand Thread

Bearing Bore Code

Basic Part No.

No Letter Indicates Chromium-Molybdenum Steel Letter "CR" Indicates SUS630 for Body

Notes

- (1) Axial load indicates either the smaller value of static load or proof load.
- (2) Special specification can bare higher fatigue load.
- 3. Made to order only.
- 4. Radial Clearance All Size: 0.051mm MAX
- ◯ Please consult MINEBEA for availability of bearings in this series.

Dimensions in mm

4 PIECE ROD END BEARING 〔METAL TO METAL〕

Basic Part No.

Dimensions in mm

| MINEBEA Part No. | ϕ B H7 | φD ± 0.5 | W -0.13 | н ± 0.13 | F ± 0.5 | TH JIS Class 2 | ± 0.7 | α (deg.) | ϕ O Ref. | S ϕ DB Ref. | Radial Static Limit Load kN | Static Ultimate Load kN | Approx. Weight |
|-------------------------------|----------------|-------------|----------------|-------------|------------|---------------------------------|-------|-----------------------------|------------------|-----------------------|--|--|-------------------|
| (1) PR3E | B | 12 | 6 | 4.50 | 27 | $M3 \times 0.5$ | 15 | 14 | 5.2 | 7.94 | 1.56 | 2.45 | |
| (1) PR4E | $\overline{4}$ | 14 | | 5.25 | 30 | $MA \times 0.7$ | 17 | | 6.5 | 9.52 | 2.25 | 3.53 | 10 ¹ |
| PR _{5E} | 5. | 16 | 8 ¹ | 6.00 | 33 | $M5 \times 0.8$ | 20 | 13 | 7.7 | 11.11 | 4.51 | 7.06 | 13 |
| PR6E | 6 | 18 | 9 | 6.75 | 36 | $M6 \times 1.0$ | 22 | | 9.0 | 12.70 | 6.37 | 9.90 | 19 ₁ |
| PR8E | 8 | 22 | 12 | 9.00 | 42 | $M8 \times 1.25$ | 25 | 14 | 10.4 | 15.88 | 13.72 | 21.47 | 32 ² |
| PR10E | 10 | 26 | 14 | 10.50 | 48 | $M10 \times 1.5$ | 29 | 13 | 12.9 | 19.05 | 18.82 | 29.41 | 54 |
| PR12E | 12 | 30 | 16 | 12.00 | 54 | $M12 \times 1.75$ | 33 | | 15.4 | 22.22 | 25.20 | 39.42 | 85 |
| PR _{14E} | 14 | 34 | 19 | 13.50 | 60 | $M14 \times 2.0$ | 36 | 16 | 16.9 | 25.40 | 30.49 | 47.75 | 126 |
| PR _{16E} | 16 | 38 | 21 | 15.00 | 66 | $M16 \times 2.0$ | 40 | 15 | 19.4 | 28.58 | 38.04 | 59.64 | 185 |
| PR18E | 18 | 42 | 23 | 16.50 | 72 | $M18 \times 1.5$ | 44 | | 21.9 | 31.75 | 46.28 | 72.47 | 258 |
| PR _{20E} | 20 | 46 | 25 | 18.00 | 78 | $M20 \times 1.5$ | 47 | 14 | 24.4 | 34.92 | 53.83 | 84.33 | 340 |
| PR _{22E} | 22 | 50 | 28 | 20.00 | 84 | $M22 \times 1.5$ | 51 | 15 | 25.8 | 38.10 | 63.93 | 100.22 | 435 |

Notes

(1) Lubrication fitting are not available for PR3E, PR4E.

2. Radial Clearance Standard Clearance: 0.051mm MAX Low Clearance: 0.030mm MAX

4 PIECE ROD END BEARING 〔METAL TO METAL〕

Mineb eMINEBEA.COM

Basic Part No.

Dimensions in mm

Notes

(1) Lubrication fitting are not available for PR3, PR4.

2. Radial Clearance

Standard Clearance: 0.051mm MAX Low Clearance: 0.030mm MAX

MOLDED ROD END BEARING 〔SELF-LUBRICATING〕

ROD END BEARING MOLDED MINELON TN

Materials

BODY Low Carbon Steel / Zinc Plated BALL Bearing Steel / Heat Treated / Chrome Plated LINER Minelon TN

 Π

Description of Types

RBM L xx E

Bearing Bore Code

No Letter Indicates Right Hand Thread Letter "L" Indicates Left Hand Thread Basic Part No.

Dimensions in mm

Notes

- ① Operating temperature range: 50 ℃~+ 100 ℃
- ② Dynamic Load Ratings: Cd
- 1. Reversing & Alternating Load Dynamic Load Ratings shall be reduced by half from the values given in the table under the use of reversing and alternating load condition.
- 2. Factor of Operating Temperature and Sliding Speed Dynamic Load Ratings shall be determined by formula below under the use of High-Temperature and Sliding-Speed condition. Cdt・v=ft・fv・Cd

Cdt · v: Dynamic Load Ratings under the use of High-

- Temperature and Sliding speed.
- ft: Coefficient of Temperature
- fv: Coefficient of Sliding speed

Table 1

③ Static Load Ratings: Cs

- 1. Dynamic Load Ratings shall be reduced to one-thirds of the values given in the table under the use of that High-Load will be applied continiously or periodically and be reduced to one-sixth of the values given under Reversing and Alternating Load and Impact Load conditions.
- 2. Factor of Operating Temperature Dynamic Load Ratings shall be determined by formula below under the use of High-Temperature conditions. Cs・t=ft・Cs Cs・t: Dynamic Load Ratings under the use of High-
	- Temperature condition.
	- ft: Coefficient of Temperature
	- Cs: Static Load given in the table

Table 3

 \bigcap Please consult MINEBEA for availability of bearings in this series.

 $+ 15$ 0

Table 2

 $+21$ Ω

+ 18 Ω

MOLDED ROD END BEARING 〔SELF-LUBRICATING〕

RBM

BODY Low Carbon Steel / Zinc Plated

- BALL Bearing Steel / Heat Treated / Chrome Plated
- LINER Minelon

Description of Types

RBM L XX Bearing Bore Code No Letter Indicates right hands Letter "L" Indicates left hands Basic Part No.

Dimensions in mm

eMINEBEA.COM

Vine

Notes

- ① Operating temperature range: 50 ~+ 100 ℃
- ② Dynamic Load Ratings: Cd
- 1. Reversing & Alternating Load Dynamic Load Ratings shall be reduced by half from the values given in the table under the use of reversing and alternating load condition.
- 2. Factor of Operating Temperature and Sliding Speed Dynamic Load Ratings shall be determined by formula below under the use of High-Temperature and Sliding-Speed condition. Cdt・v=ft・fv・Cd Cdt・v: Dynamic Load Ratings under the use of High-

Temperature and Sliding speed. ft: Coefficient of Temperature fv: Coefficient of Sliding speed

Table 1

Table 2

- ③ Static Load Ratings: Cs
- 1. Dynamic Load Ratings shall be reduced to one-thirds of the values given in the table under the use of that High-Load will be applied continiously or periodically and be reduced to one-sixth of the values given under Reversing and Alternating Load and Impact Load conditions.
- 2. Factor of Operating Temperature Dynamic Load Ratings shall be determined by formula below under the use of High-Temperature conditions. Cs・t=ft・Cs Cs・t: Dynamic Load Ratings under the use of High-Temperature condition. ft: Coefficient of Temperature Cs: Static Load given in the table

Table 3

SLEEVE BEARING [SELF-LUBRICATING] **MJ-A,MJ-C** SLEEVE BEARING TFE LINED PLAIN TYPE

Materials

MJ-A MJ-C

SLEEVE Aluminium Alloy Anodised or Alodined 410 Stainless Steel

LINER TFE TELEVISION TO THE TELEVISION OF THE TELEVISION OF THE TELEVISION OF THE TELEVISION OF THE TELEVISION

Description of Types

MJ xx x xx

Length Code Material Code (A, C)

Bore Code

Basic Part No.

Dimensions in mm

Notes

- 1. Teflon liner permanently bonded to Sleeve I.D.
- (2) (a) Tolerances: Aluminium ± 0.013

Stainless steel 0 to -0.013

- I.D. Size shall be inspected by plug Gauge.
- 3. Made to order only.
- ◯ Please consult MINEBEA for availability of bearings in this series.

R AFRC

Dimensions in mm

Anodised or Alodined

LINER TFE TEE

Description of Types

MJF xx x xx

 \rightarrow Length Code Material Code (A, C) Bore Code Basic Part No.

Notes

- 1. Teflon liner permanently bonded to sleeve I.D.
- (2) (a) Tolerances:

Aluminium \pm 0.013

- Stainless steel 0 to $-$ 0.013
- I.D. Size shall be inspected by plug Gauge.
- 3. Made to order only.
- ◯ Please consult MINEBEA for availability of bearings in this series.

Dimensions in mm

BALL ROD END BEARING [LUBRICATED] **PBR-EFN**

ROD END MALE | BALL INSERT | LOW TORQUE

Materials

Description of Types

PBR L XX EFN

Bearing Bore Code No Letter Indicates Right Hand Thread Letter "L" Indicates Left Hand Thread Basic Part No.

Dimensions in mm

Notes

1. Made to order only.

2. Lubrication: MIL-PRF-23827 (yellow) grease

3. Radial Clearance All Size: 0.010mm MAX

BALL ROD END BEARING (LUBRICATED) **PBR-FN**

ROD END FEMALE BALL INSERT LOW TORQUE

Materials

Description of Types

PBR L XX FN

Bearing Bore Code No Letter Indicates Right Hand Thread
Letter "L" Indicates Left Hand Thread Basic Part No.

Dimensions in mm

Notes

1. Made to order only.

2. Lubrication: MIL-PRF-23827 (yellow) grease

3. Radial Clearance All Size: 0.010mm MAX

MTO & Co. AG

Produkte

Distributeur de fournitures pour l'industrie aéronautique en Rhône-Alpes 8 rue du Puits Rochefort Z.I. de Montmartre, 42100 Saint-Étienne, FRANCE +33-(0)4 77 49 36 36

Miniaturlager

Miniature Bearings Roulements miniatures

Nadellager

Needle Roller Bearings Roulements à aiguilles

Kugel & Rollenlager

Ball and Roller Bearings Roulements à billes et routeaux

Gehäuselager

Bearing Unites Paliers

Gelenklager

Spherical Plain bearings

Rotules

Rotules

Rotules

Rotules

Rotules

Rotules

Gleitlager

Plain Bearings Paliers lisses

Zubehör

Accessories

Dichtungen

Seals Joints

for more....

High Technology for Professionals

 Tel: +41 81 300 40 00 www.mtoswiss.ch Fax: +41 81 300 40 00 info**@**mtoswiss.ch